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VFD-22000\_C\_EN\_20110120

<http://www.automatedpt.com>



**VFD**  
**C2000**  
Classical Field Oriented Control AC Motor Drive



reddot design award  
winner 2010

Email: [charles@automatedpt.com](mailto:charles@automatedpt.com)

\*We reserve the right to change the information in this catalogue without prior notice

[www.delta.com.tw/industrialautomation](http://www.delta.com.tw/industrialautomation)



## Leading the Future of Drive Technology

Delta Electronics, a leading brand in drive technology, has officially launched its most cost-effective classical field oriented control in AC motor drive VFD-C2000 series. This series offers four competitive values "high efficiency, high performance, low cost of maintenance and long product life" to customers to enhance their competitive advantage while spending less cost.

### Standard Models (IP20/NEMA1)

Power range: 230V 0.75~90kW, 460V 0.75~355kW

230V (kW)	0.75	1.5	2.2	3.7	5.5	7.5	11	15	18.5	22	30	37	45	55	75	90
230V (HP)	1	2	3	5	7.5	10	15	20	25	30	40	50	60	75	100	125
Frame Size																
460V (kW)	0.75	1.5	2.2	3.7	4.0	5.5	7.5	11	15	18.5	22	30	37	45	55	75
460V (HP)	1	2	3	5	5	7.5	10	15	20	25	30	40	50	60	75	100
Frame Size																
	A				B			C			D		E		F	
	A				B			C			D		E		F	
	A				B			C			D		E		F	
	A				B			C			D		E		F	
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	A				B			C			D		E		F	
	A				B			C			D		E		F	

### Modular Design

- Various accessories options, such as I/O extension cards, encoder feedback cards, communication cards, hot-plugging LCM keypad, removable terminals and removable fan.

#### ► PG (Encoder) cards

EMC-PG010



EMC-PG01U



EMC-PG01L



EMC-PG01R



#### ■ Removable fan

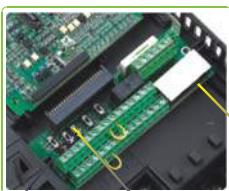
To ensure personal safety, do not begin wiring before the indicator light is off.

#### ■ Power indicator

To prevent personal injury, please do not perform wiring before power indicator is off.

#### ■ Removable terminals

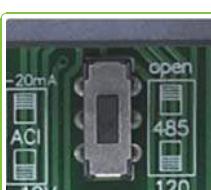
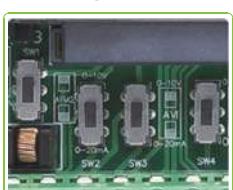
Convenient wiring and safety equipment.



Analog I/O switch

Termination resistor

Dual RJ45 communication ports



#### ► I/O cards

EMC-R6A



EMC-D42A



EMC-D611A



#### ► Communication cards

CMC-PD01



CMC-DN01



CMC-MOD01



CMC-EIP01



EMC-COP01

- The modular design fulfills the needs of system applications and equipment maintenance.



### Environmental Adaptability Design

- The built-in DC reactor and RFI filter controls harmonics and noise interference effectively.
- Strong coating to ensure safe operation in harsh environments
- Heatsink and electronics components are completely isolated from each other. With the following two heatsink designs, the best cooling according to requirements is achieved:
  - (1) Flange mounting: Heat from the drive can be dissipated out of the cabinet
  - (2) Forced fan cooling: Blow cool air into aluminum heatsink.



### ■ High-speed Network Building

- Provides various communication network cards and fieldbus cards
- Built-in RS-485 modbus protocol
- CANopen (DS402)

Supports all Delta industrial automation products (all EDS files of Delta industrial automation products are built-in)

I/O data layout of each pieces of equipments on the CANopen Network

Planning function for motion control

WPL Soft



### ■ Advanced network functions



- TAP-CN03 distribution box for long distances
- RJ45 cable

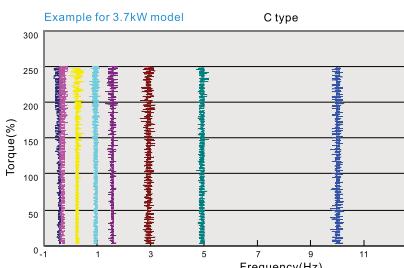
### ■ Enhanced Motor Efficiency in General Applications

Improved sensorless vector control (SVC) response and torque control in, for example, crane applications.



### ■ High-performance Field Oriented Control

In FOC+PG mode, C2000 is capable of creating a start-up torque up to 200% at extremely low speed to result a much stable speed control.

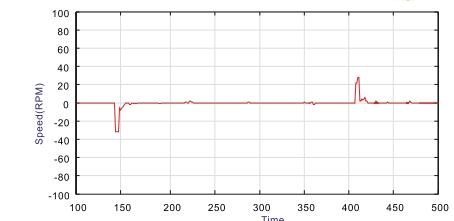


### ■ Improved Load Impact

When load changes, VFD-C2000 will provide a best torque response by FOC to minimize the vibration of load impact.

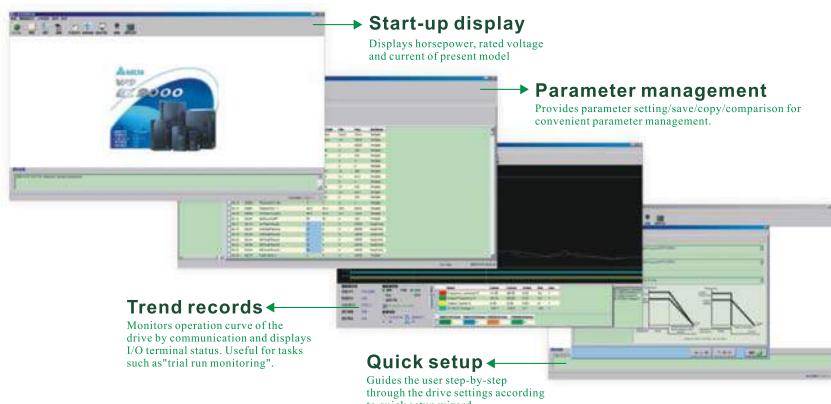


Press machine



### ■ Convenient Operation Platform for Drive System Management

- Provides a complete operation platform for users' easy control and monitoring via PC, including parameters save/setting, real-time wave monitor, quick setup, for multiple languages and with multi-language operation systems.



### ■ Safe Stop Function

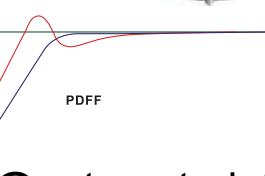
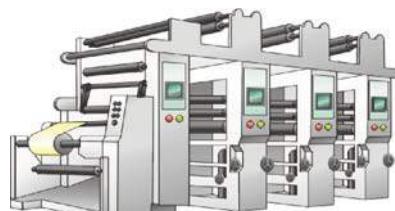
VFD-C2000 series is built according to category safe stop standard: EN954-1, EN60204-1 and IEC6158 to prevent personal injury at accidental start-up.

#### Emergency stop switch



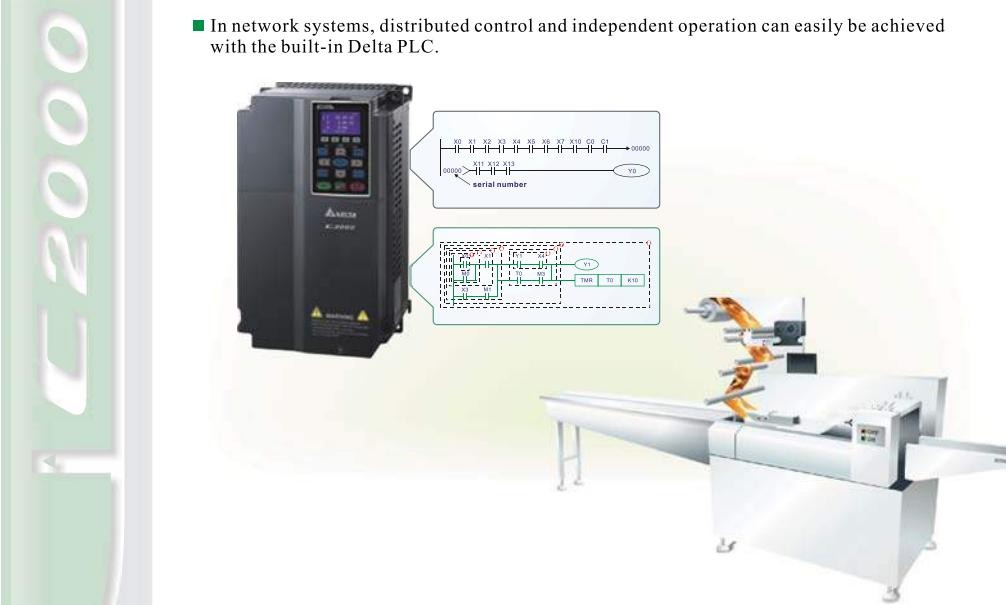
### ■ High-performance Field Oriented Control

A best choice for precise position and speed control, applicable to e.g. control printing machine.



### ■ Innovative PID Technology

Apart from traditional PI control, VFD-C2000 also provides PDFF control in speed regulation to eliminate overshoot and increase response time.



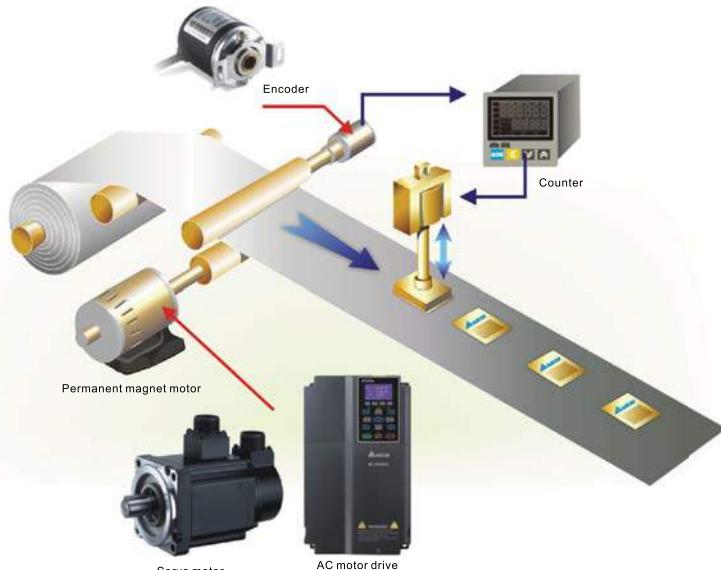
### Environment for Operation, Storage and Transportation

DO NOT expose the AC motor drive in the bad environment, such as dust, direct sunlight, corrosive/ inflammable gasses, humidity, liquid and vibration environment. The salt in the air must be less than 0.01mg/cm<sup>3</sup> every year.

Environment	Installation location	IEC60364-1/IEC60664-1 Pollution degree 2, Indoor use only
	Surrounding Temperature	No-condensation, non-frozen -25°C ~ +70°C
Rated Humidity	Operation	Max. 90%
	Storage/ Transportation	Max. 95%
Air Pressure	No condense water	
	Operation/ Storage	86 to 106 kPa
Pollution Level	Transportation	70 to 106 kPa
	IEC60721-3-3	
Altitude	Operation	Class 3C2 : Class 3S2 If AC motor drive is installed at altitude 0~1000m, follow normal operation restriction. If it is install at altitude 1000~3000m, decrease 2% of rated current or lower 0.5°C of temperature for every 100m increase in altitude. Maximum altitude for Corner Grounded is 2000m.
	Storage/ Transportation	ISTA procedure 1A(according to weight) IEC60068-2-31
Vibration	1.0mm, peak to peak value range from 2Hz to 13.2 Hz; 0.7G~1.0G range from 13.2Hz to 55Hz; 1.0G range from 55Hz to 512 Hz. Comply with IEC 60068-2-6	
Impact	IEC/EN 60068-2-27	
Operation Position	Max. allowed offset angle ± 10° (under normal installation position)	

### A Drive for Permanent Magnet (PM) Motors

VFD-C2000 is a dual mode drive for induction motors and permanent magnet motors. The dynamic response of a PM motor provides precise control of position, speed and torque.



### Specification for Operation Temperature and Protection Level

Model	Frame	Top cover	Conduit Box	Protection Level	Operation Temperature
VFDxxxCxxA	Frame A~C 230V: 0.75~22kW 460V: 0.75~30kW	Remove top cover Standard with top cover	Standard conduit plate	IP20/UL Open Type IP20/UL Type1/NEMA1	-10°C ~50°C -10°C ~40°C
	Frame D~H 230V: >22kW 460V: >30kW	N/A	No conduit box	IP00 IP20/UL Open Type	-10°C ~50°C
VFDxxxCxxE	Frame A~C 460V: 0.75~30kW	Remove top cover Standard with top cover	Standard conduit plate	IP20/UL Open Type IP20/UL Type1/NEMA1	-10°C ~50°C -10°C ~40°C
	Frame D~H 230V: >22kW 460V: >30kW	N/A	Standard conduit box	IP20/UL Type1/NEMA1	-10°C ~40°C

Only the circled area is IP00, others are IP20.

## ■ Specifications

**NOTE:**

• \*Frame F~H is under development.

- For FRAME A, B and C, Model VFXXXXC43A is under IP20/NEMA1/UL TYPE1 protection level.
- For FRAME D and above, if the last character of the model is A then it is under IP20 protection level but the wiring terminal is under IP00 protection level;

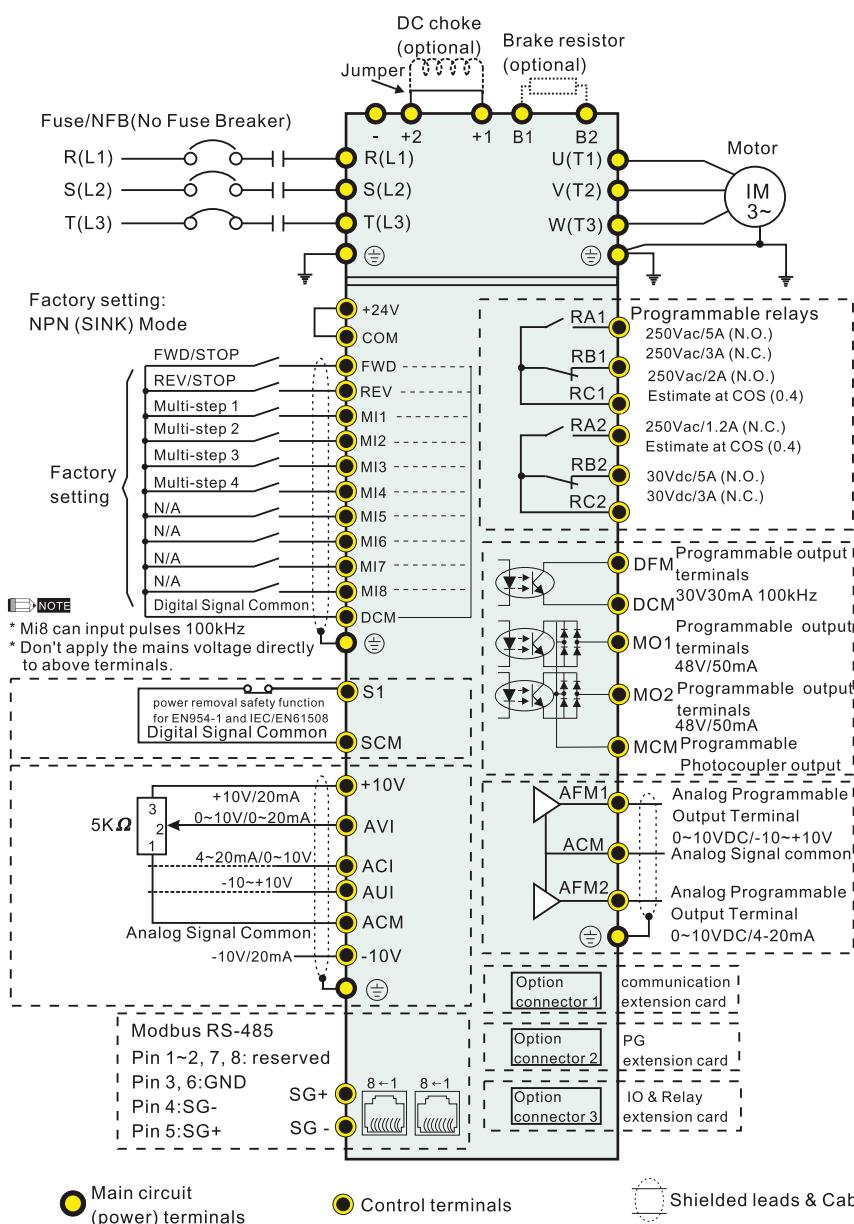
**- For FRAME D and above, if the last character of the model is A then it is under IP20 protection**  
**- if the last character of the model is E, it is under IEC20/NEMA 1/UL TYPE1 protection level**

## General Specifications

Control Characteristics	Control Method Starting Torque V/f Curve Speed Response Ability Torque Limit Torque Accuracy Max. Output Frequency (Hz) Frequency Output Accuracy Output Frequency Resolution Overload Tolerance Frequency Setting Signal Accel./decel. Time	1: V/F, 2: SVC, 3: VF+PG, 4: FOC+PG, 5: TQC+PG, Reach up to 150% or above at 0.5Hz. Under FOC+PG mode, starting torque can reach 150% at 0Hz. 4-point adjustable V/f curve and square curve 5Hz (vector control can reach up to 40Hz) Max. 200% torque current ±5% Normal duty:0.01~600.00Hz; Heavy duty: 0.00 ~ 300.00Hz Digital command:±0.01%, -10°C ~+40°C, Analog command:±0.1%, 25±10°C Digital command:0.01Hz · Analog command: 0.03 X max. output frequency/60 Hz (±11 bit) Normal duty: rated output current is 120% for 60seconds Heavy duty: rated output current is 150% for 60seconds +10V~-10.0,+10V,4~20mA,0~20mA,Pulse input 0.00~600.00/0.0~6000.0 Seconds
Main Control Function	Torque control, Droop control, Speed/torque control switching, Feed forward control, Zero-servo control, Momentary power loss ride thru, Speed search, Over-torque detection, Torque limit, 17-step speed (max), Accel/decel time switch, S-curve accel/decel, 3-wire sequence, Auto-Tuning (rotational, stationary), Dwell, Cooling fan on/off switch, Slip compensation, Torque compensation, JOG frequency, Frequency upper/lower limit settings, DC injection braking at start/stop, High slip braking, PID control (with sleep function), Energy saving control, MODOBUS communication (RS-485 RJ45, max. 115.2 kbps), Fault restart, Parameter copy	
Fan Control	230V model : VFD150C23A(include) and series above: PMW control; VFD150C23A and series below: on/off switch control 460V model : VFD150C23A(include) and series above: PMW control; VFD150C23A and series below: on/off switch control	
Protection Characteristics	<p><b>Motor Protection</b></p> <p>Over-current Protection</p> <p>Over-voltage Protection</p> <p>Over-temperature Protection</p> <p>Stall Prevention</p> <p>Restart after Instantaneous Power Failure</p> <p>Grounding Leakage Current Protection</p>	
	<p>Electronic thermal relay protection</p> <p>Over-current protection for 220% rated current current clamp "Normal duty: around 170~175%" : "Heavy duty: around 180~185%"</p> <p>230: drive will stop when DC-BUS voltage exceeds 410V 460: drive will stop when DC-BUS voltage exceeds 820V</p> <p>Built-in temperature sensor</p> <p>Stall prevention during acceleration, deceleration and running independently.</p> <p>Parameter setting up to 20 seconds</p> <p>Leakage current is higher than 50% of rated current of the AC motor drive</p>	

## Wiring

Frame A~C  
Offers 3-phase power supply

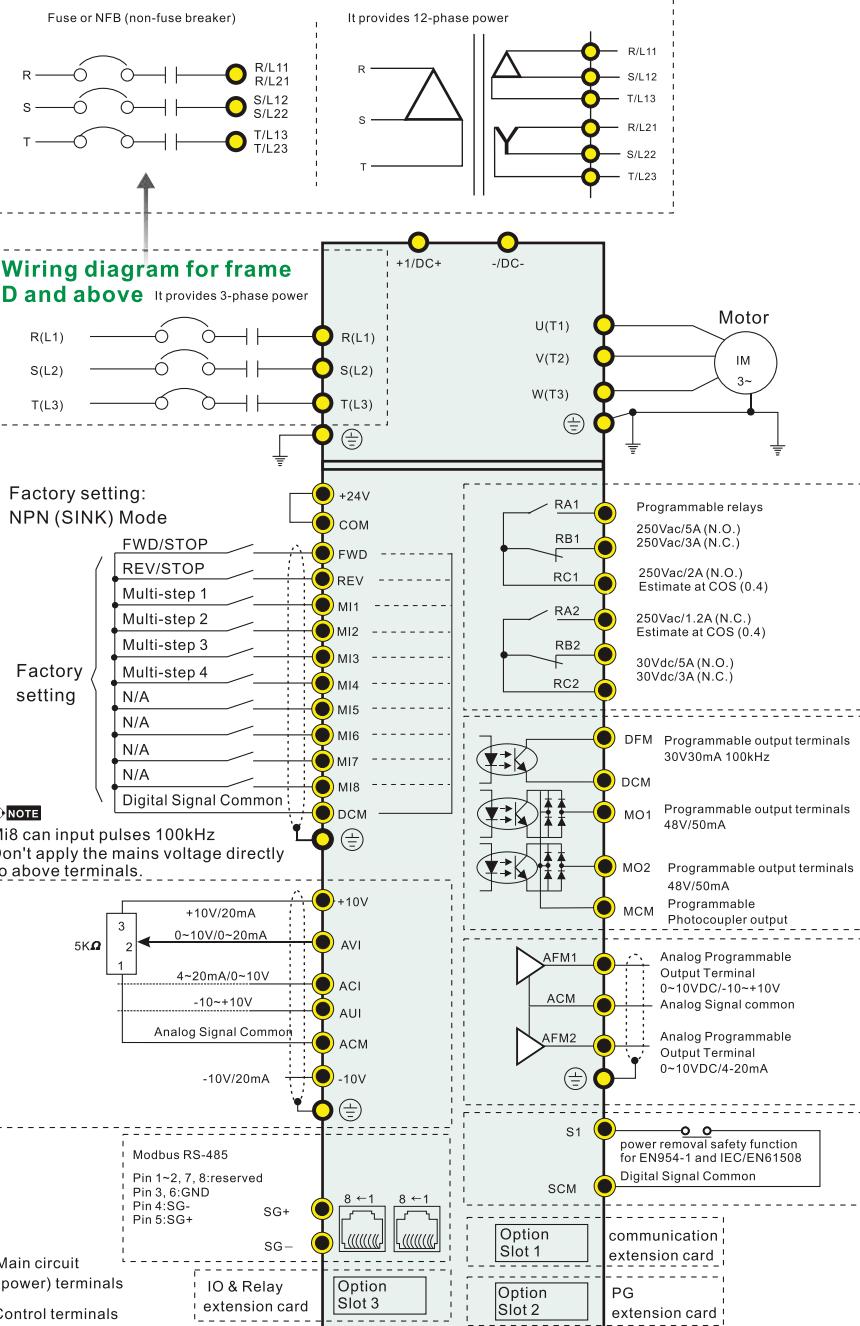


Main circuit  
(power) terminals

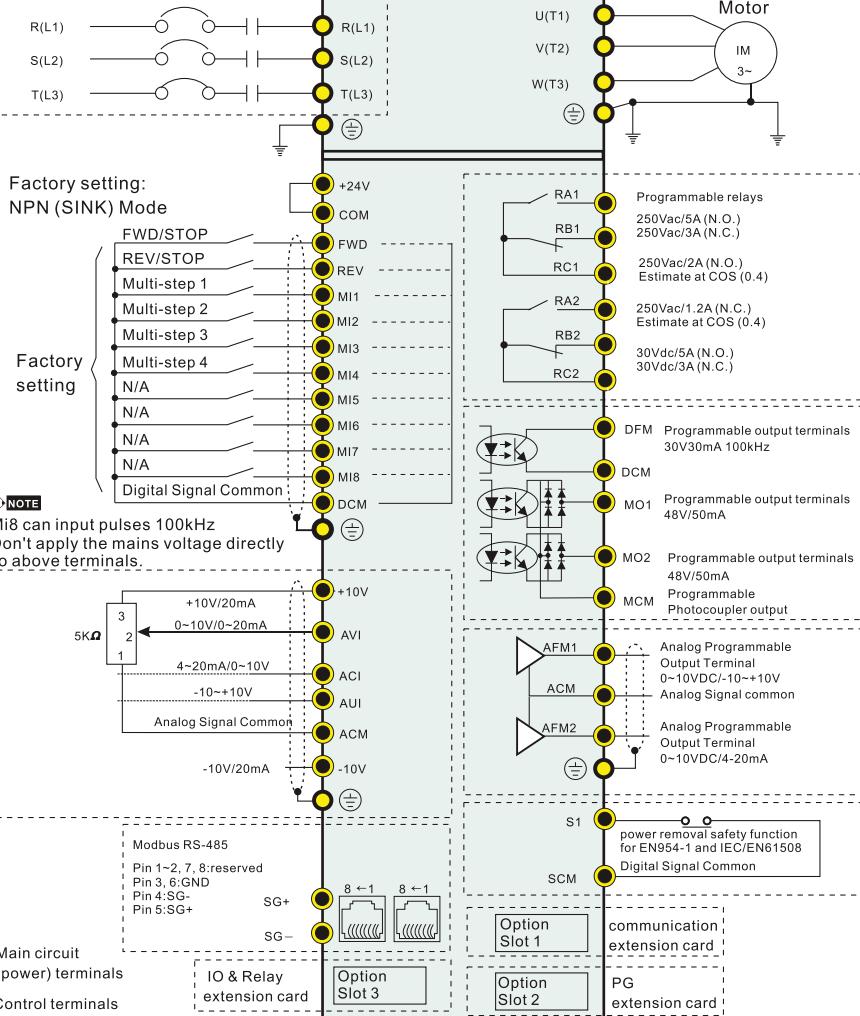
Control terminals

Shielded leads & Cable

**Input power terminals for frame G and H**  
**Provides 3-phase power**



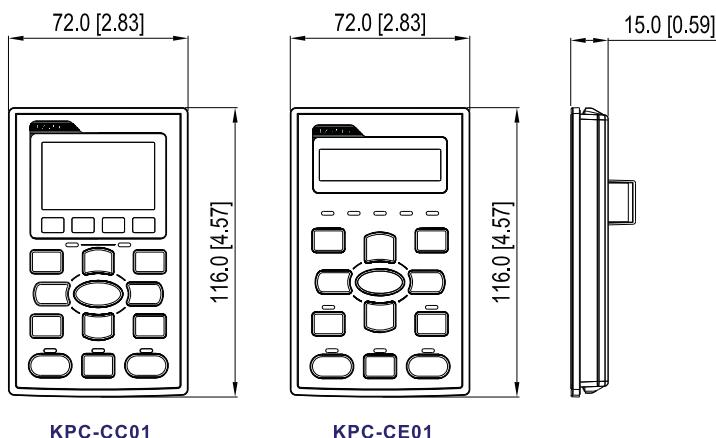
**Wiring diagram for frame D and above**  
**It provides 3-phase power**



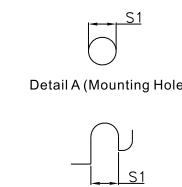
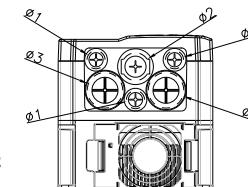
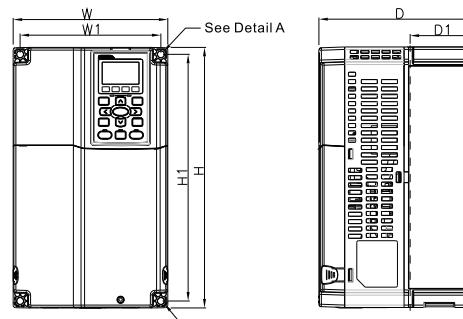
1C2000

## Dimensions

## ■ Digital Keypad



## ■ Frame B



Unit : mm[inch]

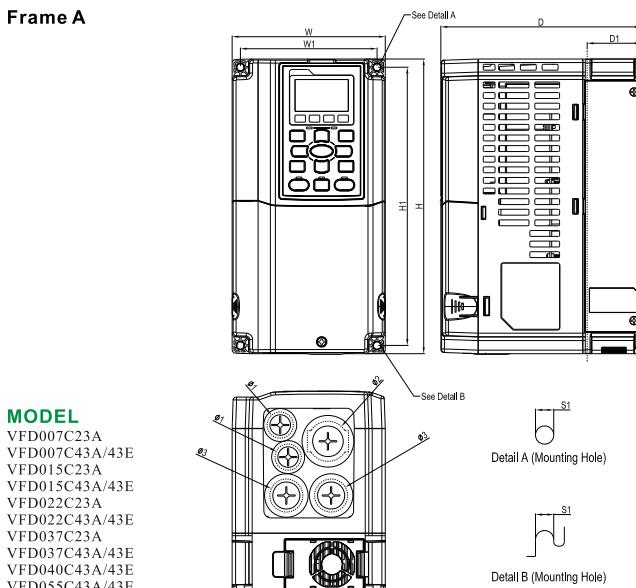
## MODEL

VFD055C23A  
VFD075C23A  
VFD075C43A/43E  
VFD110C23A  
VFD110C43A/43E  
VFD150C43A/43E

Frame	W	H	D	W1	H1	D1*	S1	Ø1	Ø2	Ø3
B1	mm	190.0	320.0	190.0	173.0	303.0	77.9	8.5	22.2	34.0
	inch	7.48	12.60	7.48	6.81	11.93	3.07	0.33	0.87	1.34

NOTE: Model VFD075C43E; VFD110C43E; VFD150C43E will be available for ordering soon. Please contact your local distributor or Delta representative for detailed launch schedule.

## ■ Frame A



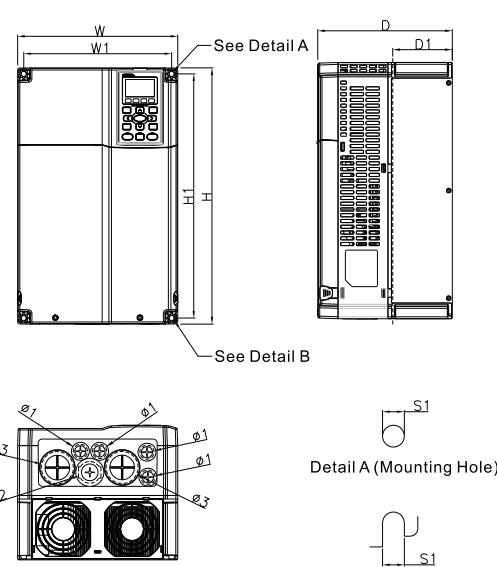
## MODEL

VFD007C23A  
VFD007C43A/43E  
VFD015C23A  
VFD015C43A/43E  
VFD022C23A  
VFD022C43A/43E  
VFD037C23A  
VFD037C43A/43E  
VFD040C43A/43E  
VFD055C43A/43E

Frame	W	H	D	W1	H1	D1*	Ø	Ø1	Ø2	Ø3
A1	mm	130.0	250.0	170.0	116.0	236.0	45.8	6.2	22.2	34.0
	inch	5.12	9.84	6.69	4.57	9.29	1.80	0.24	0.87	1.34

NOTE: Model VFD007C43E; VFD015C43E; VFD022C43E; VFD037C43E; VFD040C43E; VFD055C43E will be available for ordering soon. Please contact your local distributor or Delta representative for detailed launch schedule.

## ■ Frame C



## MODEL

VFD150C23A  
VFD185C23A  
VFD185C43A/43E  
VFD220C23A  
VFD220C43A/43E  
VFD300C43A/43E

Frame	W	H	D	W1	H1	D1*	S1	Ø1	Ø2	Ø3
C1	mm	250.0	400.0	210.0	231.0	381.0	92.9	8.5	22.2	34.0
	inch	9.84	15.75	8.27	9.09	15.00	3.66	0.33	0.87	1.34

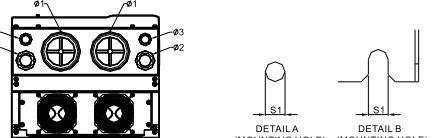
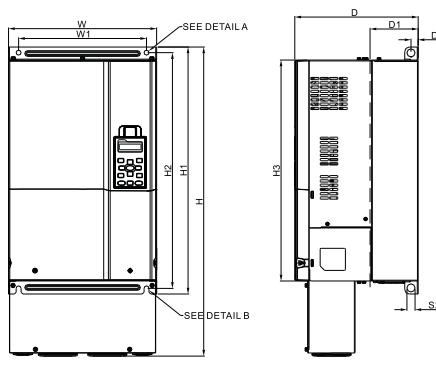
NOTE: Model VFD185C43E; VFD220C43E; VFD300C43E will be available for ordering soon. Please contact your local distributor or Delta representative for detailed launch schedule.

D1\*: Flange mounting

C2000

## Dimensions

## Frame D



## MODEL

## FRAME\_D1

VFD300C23A  
VFD370C23A  
VFD370C43A  
VFD450C43A  
VFD550C43A  
VFD750C43A

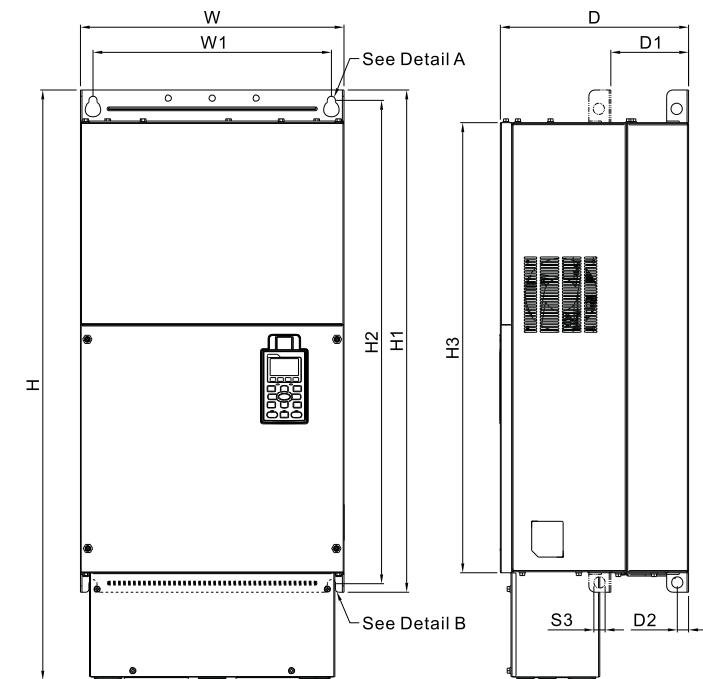
## FRAME\_D2

VFD300C23E  
VFD370C23E  
VFD370C43E  
VFD450C43E  
VFD550C43E  
VFD750C43E

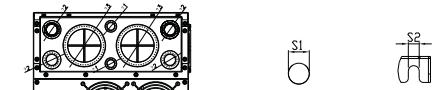
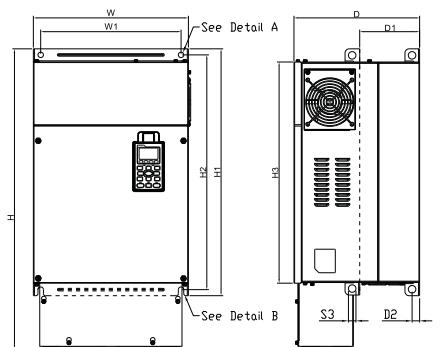
Frame	W	H	D	W1	H1	H2	H3	D1*	D2	S1	S2	Ø1	Ø2	Ø3
D1	330.0 [12.99]	- [10.83]	275.0 [11.22]	285.0 [21.65]	550.0 [20.67]	525.0 [19.37]	492.0 [4.22]	107.2 [0.63]	16.0 [0.43]	11.0 [0.43]	18.0 [0.71]	- [0.71]	- [0.71]	- [0.71]
D2	330.0 [12.99]	688.3 [27.10]	275.0 [10.83]	285.0 [11.22]	550.0 [21.65]	525.0 [20.67]	492.0 [19.37]	107.2 [4.22]	16.0 [0.63]	11.0 [0.43]	18.0 [0.71]	76.2 [3.00]	34.0 [1.34]	22.0 [0.87]

Unit : mm[inch]

## Frame F



## Frame E



## MODEL

## FRAME\_E1

VFD450C23A  
VFD550C23A  
VFD750C23A  
VFD900C43A  
VFD1100C43A

## FRAME\_E2

VFD450C23E  
VFD550C23E  
VFD750C23E  
VFD900C43E  
VFD1100C43E

Frame	W	H	D	W1	H1	H2	H3	D1*	D2	S1,S2	S3	Ø1	Ø2	Ø3
E1	370.0 [14.57]	- [11.81]	300.0 [13.19]	335.0 [23.19]	589 [22.05]	560.0 [20.80]	528.0 [5.63]	143.0 [0.71]	18.0 [0.51]	13.0 [0.51]	18.0 [0.71]	- [0.71]	- [0.71]	- [0.71]
E2	370.0 [14.57]	715.8 [28.18]	300.0 [11.81]	335.0 [13.19]	589 [22.05]	560.0 [20.80]	528.0 [5.63]	143.0 [0.71]	18.0 [0.51]	13.0 [0.51]	18.0 [0.71]	22.0 [0.87]	34.0 [1.34]	92.0 [3.62]

Unit : mm[inch]

## MODEL

## FRAME\_F1

VFD900C23A  
VFD1320C23A  
VFD1600C23A

## FRAME\_F2

VFD900C23E  
VFD1320C43E  
VFD1600C43E

Frame	W	H	D	W1
F1	420.0 [16.54]	- [11.81]	300.0 [14.96]	380.0
F2	420.0 [16.54]	940.0 [37.00]	300.0 [11.81]	380.0 [14.96]

Unit : mm[inch]

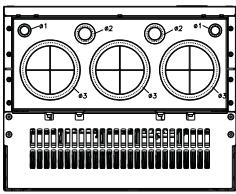
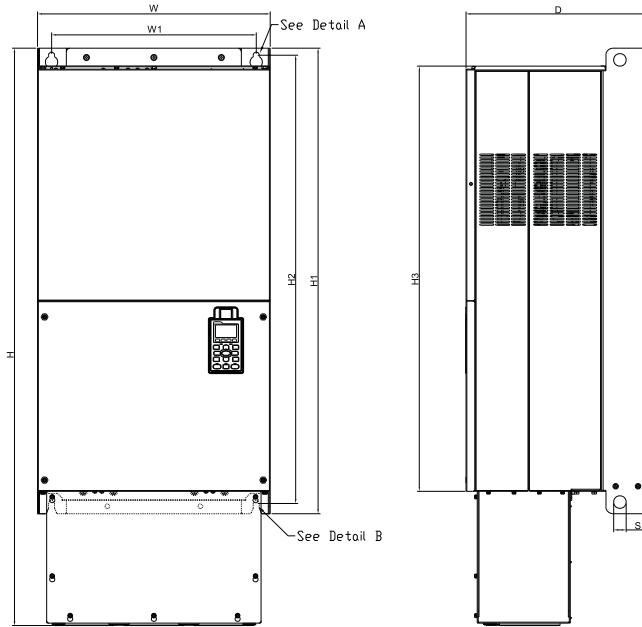
Frame	H1	H2	H3	D1*	D2	S1	S2	S3	Ø1	Ø2	Ø3
F1	800.0 [31.50]	770.0 [30.32]	717.0 [28.23]	124.0 [4.88]	18.0 [0.71]	13.0 [0.51]	25.0 [0.98]	18.0 [0.71]	92.0 [3.62]	35.0 [1.38]	22.0 [0.87]
F2	800.0 [31.50]	770.0 [30.32]	717.0 [28.23]	124.0 [4.88]	18.0 [0.71]	13.0 [0.51]	25.0 [0.98]	18.0 [0.71]	92.0 [3.62]	35.0 [1.38]	22.0 [0.87]

Unit : mm[inch]

D\*: Flange mounting

### Dimensions

#### ■ Frame G

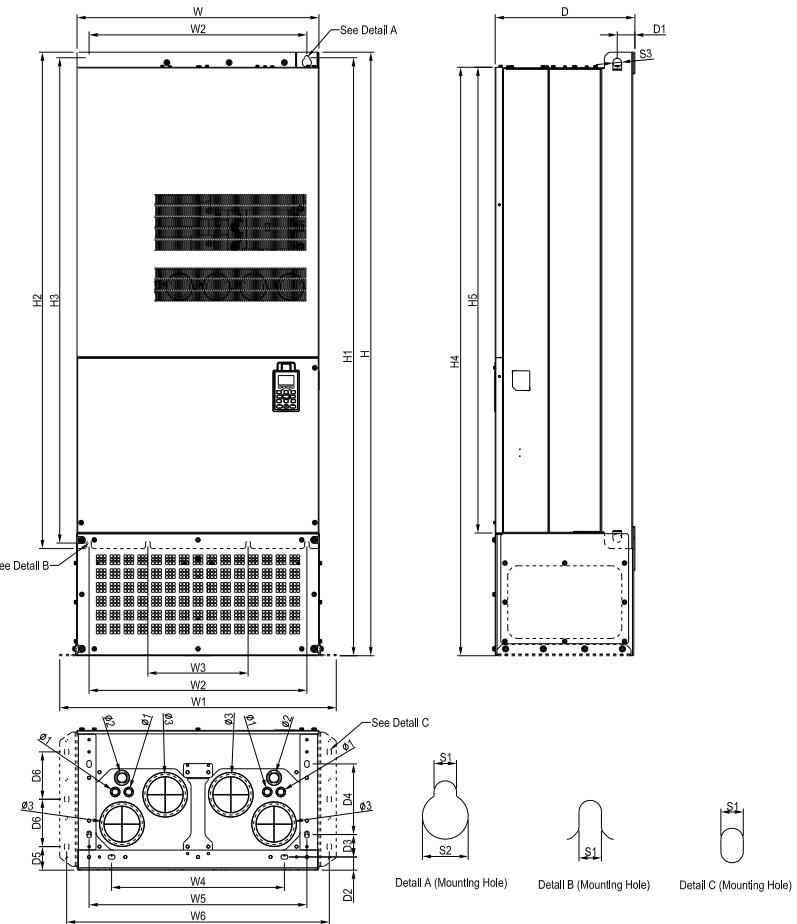


Detail A (Mounting Hole)



Detail B (Mounting Hole)

#### ■ Frame H



#### MODEL

##### FRAME\_H1

VFD2800C43A  
VFD3150C43A  
VFD3550C43A

##### FRAME\_H2

VFD2800C43E-1  
VFD3150C43E-1  
VFD3550C43E-1

##### FRAME\_H3

VFD2800C43E  
VFD3150C43E  
VFD3550C43E

Unit : mm[inch]

#### MODEL

**FRAME\_G1**  
VFD1850C43A  
VFD2200C43A

**FRAME\_G2**  
VFD1850C43E  
VFD2200C43E

Frame	W	H	D
G1	500.0 [19.69]	-	397.0 [15.63]
G2	500.0 [19.69]	1240.2 [48.83]	397.0 [15.63]

Unit : mm[inch]

Frame	W1	H1	H2	H3	S1	S2	S3	Ø1	Ø2	Ø3
G1	440.0 [217.32]	1000.0 [39.37]	963.0 [37.91]	913.6 [35.97]	13.0 [0.51]	26.5 [1.04]	27.0 [1.06]	-	-	-
G2	440.0 [217.32]	1000.0 [39.37]	963.0 [37.91]	913.6 [35.97]	13.0 [0.51]	26.5 [1.04]	27.0 [1.06]	22.0 [0.87]	34.0 [1.34]	117.5 [4.63]

IC2000

### Option Cards

#### EMC-D42A



I/O Extension Card

Terminals	Descriptions
COM	Common for multi-function input terminals Select SINK (NPN) /SOURCE (PNP) in J1 jumper / external power supply
MI10~ MI13	Refer to parameters 02-26~02-29 to program the multi-function inputs MI10~MI13. Internal power is applied from terminal E24: +24Vdc±5% 200mA, 5W External power +24Vdc: max. voltage 30Vdc, min. voltage 19Vdc, 30W ON: the activation current is 6.5mA OFF: leakage current tolerance is 10µA
MO10~MO11	Multi-function output terminals (photocoupler) Duty-cycle: 50% Max. output frequency: 100Hz Max. current: 50mA Max. voltage: 48Vdc
MXM	Common for multi-function output terminals MO10, MO11(photocoupler) Max 48Vdc 50mA

#### EMC-D611A



I/O Extension Card

Terminals	Descriptions
AC	AC power common for multi-function input terminal (Neutral)
MI10~ Mi15	Refer to Pr. 02.26~ Pr. 02.31 for multi-function input selection Input voltage: 100~130VAC Input frequency: 57~63Hz Input impedance: 27Kohm Terminal response time: ON: 10ms OFF: 20ms

#### EMC-R6AA



Relay Extension Card

Terminals	Descriptions
R10A~R15A R10C~R15C	Refer to Pr. 02.36~ Pr. 02.41 for multi-function input selection Resistive load: 5A(N.O.)/3A(N.C.) 250VAC 5A(N.O.)/3A(N.C.) 30Vdc Inductive load (COS 0.4) 2.0A(N.O.)/1.2A(N.C.) 250VAC 2.0A(N.O.)/1.2A(N.C.) 30Vdc It is used to output each monitor signal, such as for drive in operation, frequency attained or overload indication.

#### EMC-PG01L



Set by Pr.10-00~10-02

Terminals	Descriptions
PG1	VP Output voltage for power: +5V/+12V±5% (use FSW3 to switch +5V/+12V) Max. output current: 200mA
	DCM Common for power and signal
	A1, /A1 B1, /B1 Z1, /Z1 Encoder Input signal It can be 1-phase or 2-phase input. Max. output frequency: 300kP/sec
PG2	A2, /A2 B2, /B2 Pulse Input signal It can be 1-phase or 2-phase input. Max. output frequency: 300kP/sec.
PG OUT	AO, /AO BO, /BO ZO, /ZO PG Card Output signals. It has division frequency function: 1~255 times Max. output voltage for Line driver: 5Vdc Max. output current: 50mA Max. output frequency: 300kP/sec

#### EMC-PG01O



Set by Pr.10-00~10-02

Terminals	Descriptions
PG1	VP Output voltage for power: +5V/+12V±5% (use FSW3 to switch +5V/+12V) Max. output current: 200mA
	DCM Common for power and signal
	A1, /A1 B1, /B1 Z1, /Z1 Encoder Input signal It can be 1-phase or 2-phase input. Max. output frequency: 300kP/sec
PG2	A2, /A2 B2, /B2 Pulse Input Signal It can be 1-phase or 2-phase input. Max. output frequency: 300kP/sec.
V+	Needs external power source for PG OUT circuit. Input voltage of power:+12V ~ +24V
PG OUT	A/O, B/O, /IO PG Card Output signals. It has division frequency function: 1~255 times Input signal of open collector. Please add a pull-high resistor on the external power V+~V-(e.g. power of PLC) to prevent the interference of the receiving signal. Max. Output current: 20mA. Max output frequency: 300KP/Sec

#### EMC-PG01R



Set by Pr.10-00~10-02

Terminals	Descriptions
PG1	R1- R2 Resolver Output Power 7Vrms, 10kHz
	S1,S2, S3, S4, Resolver Input Signal 3.5±0.175Vrms, 10kHz
PG2	A2, /A2 B2, /B2 Pulse Input Signal It can be 1-phase or 2-phase input. Max. output frequency: 300kP/sec.
PG OUT	AO, /AO, BO /BO, ZO, /ZO PG Card Output signals. It has division frequency function: 1~255 times Max. output voltage for Line driver: 5Vdc Max. output current: 50mA Max. output frequency: 300kP/sec

#### Screw Specifications for Option card Terminals:

EMC-D42A	Wire gauge	24~12AWG (0.205~3.31mm <sup>2</sup> )
	Torque	4Kg·cm [3.47lb-in]
EMC-R6AA	Wire gauge	24~16AWG (0.205~1.31mm <sup>2</sup> )
	Torque	6Kg·cm [5.21lb-in]
EMC-PG01L EMC-PG01O EMC-PG01R EMC-PG01U	Wire gauge	30~16AWG (0.0509~1.31mm <sup>2</sup> )
	Torque	2Kg·cm [1.74lb-in]

### Option Cards

#### EMC-PG01U

- FJMP1: Standard UVW Output Encoder; D: Delta Encoder
- Set by Pr.10-00~10-02

Terminals		Descriptions
PG1	VP	Output voltage for power: +5V/+12V5% (use FSW3 to switch +5V/+12V) Max. output current: 200mA
	DCM	Common for power and signal
	A1, /A1, B1, /B1, Z1, /Z1	Encoder input signal 1-phase or 2-phase input. Max. output frequency: 300kP/sec
	U1, /U1, V1, V1, W1, /W1	Encoder input signal
PG2	A2, /A2 B2, /B2	Pulse Input signal 1-phase or 2-phase input. Max. output frequency: 300kP/sec.
PG OUT	AO, /AO, BO, /BO, ZO, /ZO	PG Card Output signals. Division frequency function: 1~255 times Max. output voltage for Line driver: 5Vdc Max. output current: 50mA Max. output frequency: 300kP/sec

#### CMC-PD01



##### Features

- Supports PZD control data exchange.
- Supports PKW polling AC motor drive parameters.
- Supports user diagnosis function.
- Auto-detects baud rates; supports Max. 12Mbps.

##### PROFIBUS DP Connector

Interface	DB9 connector
Transmission method	High-speed RS-485
Transmission cable	Shielded twisted pair cable
Electrical isolation	500VDC

##### Communication

Message type	Cyclic data exchange
Module name	CMC-PD01
GSD document	DELA08DB.GSD
Company ID	08DB (HEX)
Serial transmission speed supported (auto-detection)	9.6kbps; 19.2kbps; 93.75kbps; 187.5kbps; 125kbps; 250kbps; 500kbps; 1.5Mbps; 3Mbps; 6Mbps; 12Mbps (bits per second)

#### CMC-MOD01



##### Features

- MDI/MDI-X auto-detect
- E-mail alarm
- Virtual serial port.
- Baud rate: 10/100Mbps auto-detect
- Supports Modbus TCP protocol
- AC motor drive keypad/Ethernet configuration

##### Network Interface

Interface	RJ-45 with Auto MDI/MDIX
Number of ports	1 Port
Transmission method	IEEE 802.3, IEEE 802.3u
Transmission cable	Category 5e shielding 100M
Transmission speed	10/100 Mbps Auto-Detect
Network protocol	ICMP, IP, TCP, UDP, DHCP, SMTP, MODBUS OVER TCP/IP, Delta Configuration

#### CMC-DN01



##### Features

- Based on the high-speed communication interface of Delta HSSP protocol, able to conduct immediate control of AC motor drive.
- Supports Group 2 only connection and polling I/O data exchange.
- For I/O mapping, supports Max. 32 words of input and 32 words of output.
- Supports EDS file configuration in DeviceNet configuration software.
- Supports all baud rates on DeviceNet bus: 125kbps, 250kbps, 500kbps and extendable serial transmission speed mode.
- Node address and serial transmission speed can be set up on AC motor drive.
- Power supplied from AC motor drive.

##### DeviceNet Connector

Interface	5-PIN open removable connector. Of 5.08mm PIN interval
Transmission method	CAN
Transmission cable	Shielded twisted pair cable (with 2 power cables)
Transmission speed	125kbps, 250kbps, 500kbps and extendable serial transmission speed mode
Network protocol	DeviceNet protocol

#### CMC-EIP01



##### Features

- MDI/MDI-X auto-detect
- Virtual serial port
- Supports Modbus TCP and Ethernet/IP protocol
- Baud rate: 10/100Mbps auto-detect
- AC motor drive keypad/Ethernet configuration

##### Network Interface

Interface	RJ-45 with Auto MDI/MDIX
Number of ports	1 Port
Transmission method	IEEE 802.3, IEEE 802.3u
Transmission cable	Category 5e shielding 100M
Transmission speed	10/100 Mbps Auto-Detect
Network protocol	ICMP, IP, TCP, UDP, DHCP, HTTP, SMTP, MODBUS OVER TCP/IP, EtherNet/IP, Delta Configuration

##### AC Motor Drive Connection Port

Interface	50 PIN communication terminal
Transmission method	SPI communication
Terminal function	1. Communicating with AC motor drive 2. Transmitting power supply from AC motor drive
Communication protocol	Delta HSSP protocol

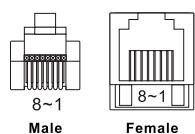
VFD2000

### ■ Option Cards

#### EMC-COP01



##### RJ-45 Pin definition



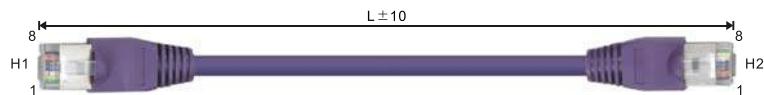
Pin	Pin name	Definition
1	CAN_H	CAN_H bus line (dominant high)
2	CAN_L	CAN_L bus line (dominant low)
3	CAN_GND	Ground/0V/V-
7	CAN_GND	Ground/0V/V-

##### Specification

Interface	RJ-45
Number of ports	1 Port
Transmission method	CAN
Transmission cable	CAN standard cable
Transmission speed	1M 500k 250k 125k 100k 50k
Communication protocol	CANopen

##### ■ CANopen Communication Cable

Model: TAP-CB03, TAP-CB04



Title	Part No.	L	
		mm	inch
1	TAP-CB03	500±10	19±0.4
2	TAP-CB04	1000±10	39±0.4

##### ■ CANopen Dimensions

Model: TAP-CN03



### ■ Ordering information



**Frame A**  
230V:  
0.75~3.7kW  
(1~6HP)  
  
460V:  
0.75~5.5kW  
(1~7.5HP)

VFD007C23A  
VFD037C23A  
VFD007C43A/E  
VFD015C43A/E  
VFD037C43A/E  
VFD040C43A/E  
VFD055C43A/E  
  
VFD015C23A/E  
VFD022C23A/E  
VFD022C43A/E



**Frame B**  
230V:  
5.5~11kW  
(7.5~15HP)  
  
460V:  
7.5~15 kW  
(10~20HP)

VFD055C23A  
VFD075C23A  
VFD110C23A/E  
VFD075C43A/E  
VFD110C43A/E  
VFD150C43A/E



**Frame C**  
230V:  
15~22 kW  
(20~30HP)  
  
460V:  
18.5~30 kW  
(25~40HP)

VFD150C23A  
VFD185C23A  
VFD220C23A  
VFD185C43A/E  
VFD220C43A/E  
VFD300C43A/E



**Frame D**  
230V:  
30~37 kW  
(40~50HP)  
  
460V:  
37~75 kW  
(50~100HP)

VFD300C23A  
VFD370C23A  
VFD370C43A  
VFD450C43A  
VFD550C43A  
VFD750C43A  
VFD300C23E  
VFD370C43E  
VFD450C43E  
VFD550C43E  
VFD750C43E



**Frame E**  
230V:  
45~55 kW  
(60~75HP)  
  
460V:  
90~110 kW  
(125~150HP)

VFD450C23A/E  
VFD550C23A/E  
VFD900C43A/E  
VFD1100C43A/E  
VFD750C23A/E



**Frame F**  
230V:  
75~90 kW  
(100~125HP)  
  
460V:  
132~160 kW  
(175~215HP)

VFD900C23A/E  
VFD1320C43A/E  
VFD1600C43A/E



**Frame G**  
230V:  
185~220 kW  
(250~300HP)

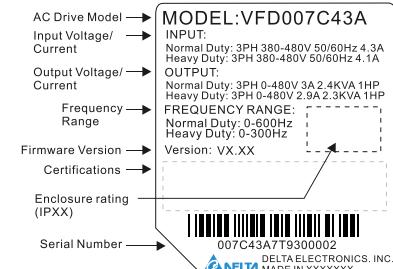
VFD1850C43A/E  
VFD2200C43A/E



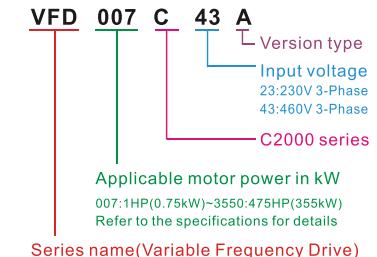
**Frame H**  
460V:  
280~355 kW  
(375~475HP)

VFD2800C43A/E  
VFD3150C43A/E  
VFD3550C43A/E

### ■ Nameplate



### ■ Model name



### ■ Optional Accessories

- ▶ Digital Keypad KPC-CE01
- ▶ Option Cards
- ▶ Fuse
- ▶ Non-fuse Circuit Breaker
- ▶ All Brake Resistors and Brake Units Used in AC Motor Drives
- ▶ AC Reactor
- ▶ Zero Phase Reactor
- ▶ DC Reactor
- ▶ EMI Filter
- ▶ Panel Mounting
- ▶ Conduit Box Kit
- ▶ Fan Kit
- ▶ Flange Mounting Kit



### Attention

#### ■ Standard Motors

- Used with 400V Standard Motors  
It is recommended to add an AC output reactor when using with a 400V standard motor to prevent damage to motor insulation.

#### • Torque Characteristics and Temperature Rise

When a standard motor is drive controlled, the motor temperature will be higher than with DOL operation.  
Please reduce the motor output torque when operating at low speeds to compensate for less cooling efficiency.  
For continuous constant torque at low speeds, external forced motor cooling is recommended.

#### • Vibration

When the motor drives the machine, resonances may occur, including machine resonances.  
Abnormal vibration may occur when operating a 2-pole motor at 60Hz or higher.

#### • Noise

When a standard motor is drive controlled, the motor noise will be higher than with DOL operation.  
To lower the noise, please increase the carrier frequency of the drive. The motor fan can be very noisy when the motor speed exceeds 60Hz.

#### ■ Special Motors

##### • High-speed Motor

To ensure safety, please try the frequency setting with another motor before operating the high-speed motor at 120Hz or higher.

##### • Explosion-proof Motor

Please use a motor and drive that comply with explosion-proof requirements.

##### • Submersible Motor & Pump

The rated current is higher than that of a standard motor.  
Please check before operation and select the capacity of the AC motor drive carefully.  
The motor temperature characteristics differ from a standard motor, please set the motor thermal time constant to a lower value.

##### • Brake Motor

When the motor is equipped with a mechanical brake, the brake should be powered by the mains supply.  
Damage may occur when the brake is powered by the drive output. Please DO NOT drive the motor with the brake engaged.

##### • Gear Motor

In gearboxes or reduction gears, lubrication may be reduced if the motor is continuously operated at low speeds. Please DO NOT operate in this way.

##### • Synchronous Motor

These motors need suitable software to control them. Please contact Delta for more information.

##### • Single-phase Motor

Single-phase motors are not suitable for being operated by an AC Motor Drive. Please use a 3-phase motor instead when necessary.

#### ■ Environmental Conditions

#### ■ Peripheral Equipment

##### • Installation Position

1. The drive is suitable for installation in a place with ambient temperature from -10 to 50°C.  
2. The surface temperature of the drive and brake resistor will rise under specific operation conditions. Therefore, please install the drive on materials that are noncombustible.

3. Ensure that the installation site complies with the ambient conditions as stated in the manual.

##### ■ Wiring

##### • Limit of Wiring Distance

For the remote operation, please use twist-shielding cable and the distance between the drive and control box should be less than 20m.

##### • Maximum Motor Cable Length

Motor cables that are too long may cause overheating of the drive or current peaks due to stray capacitance.  
Please ensure that the motor cable is less than 30m.  
If the cable length can't be reduced, please lower the carrier frequency or use an AC reactor.

##### • Choose the Right Cable

Please refer to current value to choose the right cable section with enough capacity or use recommended cables.

##### • Grounding

Please ground the drive completely by using the grounding terminal.

#### ■ How to Choose the Drive Capacity

##### • Standard Motor

Please select the drive according to applicable motor rated current listed in the drive specification.

Please select the next higher power AC drive in case higher starting torque or quick acceleration/deceleration is needed.

##### • Special Motor

Please select the drive according to:  
Rated current of the drive > rated current of the motor

##### • DO NOT Use Capacitors to Improve the Power Factor

Use a DC reactor to improve the power factor of the drive. Please DO NOT install power factor correction capacitors on the main circuit of the drive to prevent motor faults due to over current.

##### • Do NOT Use Surge Absorber

Please DO NOT install surge absorbers on the output circuit of the drive.

##### • Lower the Noise

To ensure compliance with EMC regulations, usually a filter and shielded wiring is used to lower the noise.

##### • Method Used to Reduce the Surge Current

Surge currents may occur in the phase-lead capacitor of the power system, causing an overvoltage when the drive is stopped or at low loads.

It is recommended to add a DC reactor to the drive.

#### ■ Transportation and Storage

Please transport and store the drive in a place that meets environment specifications.